

Real-Time Detection of Process Change using Process Mining

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Abstract. Process Mining is the discovery of business processes from log files. One application is ensuring conformance to prescribed processes or business rules. Since businesses operate in real time, needing to quickly react to change, processes change; but how can such changes be detected? We consider requirements for process mining to support this: a notion of real time, and methods to compare processes and detect significant change. We present initial results confirming the validity of the approach.

Keywords: Process mining, machine learning, real time, distributions.

1 Introduction

Business processes describe related activities which are carried out to fulfil a business function. Fig.1 shows an example process, depicted as a probabilistic automaton. Each directed arc is labelled with a symbol representing an activity, and the conditional probability of that activity taking place next. As the process is executed, the systems involved will record information in log files. Abstracting from detail, the ‘trace’ of a single enactment of this process might be recorded as a string of symbols *iabdefgo*. Process mining [1, 10] algorithms use logs of such traces to discover and analyse process models.

Business processes are used to manage business operations, which today take place in real time, under pressures of time, cost and competition. Processes may also ensure adherence to business rules or regulatory requirements. Divergence from these processes may therefore indicate a business problem, or have legal ramifications, and so such changes need to be detected in a timely manner.

To enable detection of process change in real-time, several requirements need to be addressed. Firstly, a definition of real time and its application to process mining; secondly, a method to measure accurately the difference between two processes; thirdly, a method to detect change in a process; and finally a notion of statistical significance of the change. We briefly address these points in section 4. First we discuss related work, then introduce a probabilistic view of business processes and process mining, which underpins the subsequent ideas.

2 Related Work

Process Mining [1, 10] has been an active area of research since the early 1990s. Typically, non-probabilistic representations are used, such as Workflow nets [11]

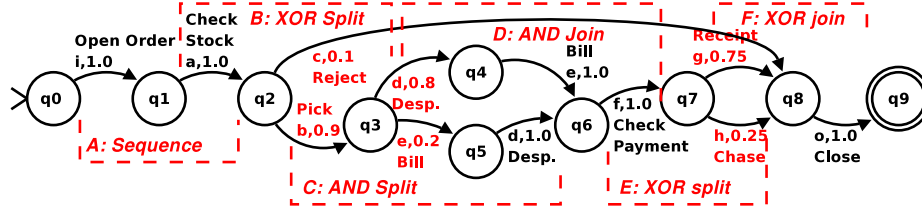


Fig. 1. PDFA showing a simplified business process for fulfilling an order.

or BPMN. Probabilistic approaches are the exception, e.g. [6]. There are three main sub-disciplines: *Process discovery* is the mining of models; *process conformance* the evaluation of results; and *extension* of models, for instance adding frequencies, mining decision rules, or predicting outcomes. We are concerned with conformance and discovery. Various algorithms have been proposed for process discovery, such as the ‘formal’ Alpha Algorithm [11]; others using heuristics, or various theoretical foundations such as Neural or Genetic [17].

‘Real-time’ is used informally in Business Process research in regard to the need for flexibility and process change to respond to a changing environment [9]. In [13, 15] process mining is part of a lifecycle of implementing and monitoring processes, finding discrepancies and resolving them, changing the model, or recommending a course of action. However, these do not discuss how much data is needed, nor how to identify when the underlying process has changed.

Other fields of research are partially related to, and may be able to inform, the work in this paper. Time series analysis [16] deals with changes to series of individual variables, whereas we are concerned with varying probability distributions over sequences. Stream mining [7] looks for patterns in data streams, and real-time data mining [5] investigates time constraints. Concept drift is the detection of change in machine learning. In [2] this is discussed in a process mining context, but with focus on model structure rather than probability.

3 A Probabilistic View of Business Processes

We model *activities* as symbols from a finite alphabet Σ , *traces* as strings $x \in \Sigma^+$, and a *process* as a probability distribution P_M over traces. Probability of trace x is $P_M(x) : \sum_{x \in \Sigma^+} P_M(x) = 1$. The task of a process mining algorithm is to learn a distribution $P_{M'}$, to approximate P_M , from the finite log W drawn *i.i.d.* from P_M . This differs from existing views of process mining, which focus on discovery of a model structure in a specific representation such as Petri nets.

We use probabilistic deterministic finite automata (PDFA) [12] (Fig.1) to represent the probability distributions generated by process models, as a common denominator to which processes in other representations can be converted. A PDFA is a five-tuple $A = (Q_A, \Sigma, \delta_A, q_0, q_F)$, where Q_A is a finite set of states; Σ an alphabet of symbols; $q_0, q_F \in Q_A$ the single start and end states; and $\delta_A : Q_A \times \Sigma \times Q_A \rightarrow [0, 1]$ is a mapping defining the conditional transition probability function between states. $\delta(q_1, a, q_2)$ is the probability that given we

are in state q_1 , we parse a and arrive in state q_2 . Given a current state and symbol, the next state is certain. Probabilities on arcs from a state sum to 1.

PDFA A generates a probability distribution P_A on Σ^+ . The probability of string x , $P_A(x)$, is found by multiplying the probabilities of the arcs followed to parse x on its unique path from the single start state q_0 to unique end state q_F .

4 Overview of Approach

4.1 Real-time Process Mining

The term ‘real time’ is used subjectively of systems which appear to process information ‘fast’. Formally, real-time systems ‘must react within precise time constraints to events in the environment’ [3]. The key is predictability and results guaranteed in a specified time, rather than speed. For us this means identifying process change as soon as possible, but with confidence that change is significant.

We consider two main constraints: accuracy and time. The mining algorithm must produce a model ‘close’ to the ‘true’ model using some notion of distance between distributions. We expect accuracy to increase with the amount of data, but for this to increase mining time. So these two constraints act in tension. We desire to minimise mining time, but characteristics of the ground truth distribution will determine the minimum data needed for confidence in mining accuracy.

This lower bound on data ensures we use the correct baseline, against which to measure change. Although an upper bound can be set on the mining time, this will be constrained by the overhead of the algorithm, the time taken to process each trace, and by the desired accuracy. The Alpha algorithm [11] which we use here is quite efficient (linear in the size of the log, exponential in the number of tasks, which is typically very restricted), so the upper bound is of less import. Other algorithms such as the Genetic Miner [17] have much higher time complexity. Factors such as these must affect the choice of algorithm.

There are other issues which we do not consider, such as from the type or magnitude of change, predicting the time to detect it; or environmental issues which may affect the real time behaviour of the system [3].

4.2 Determining the Amount of Data Needed for Mining

One way to determine the amount of data needed is to consider the structures in a process (highlighted in Fig.1), and the probability of an algorithm discovering these structures. In [14] we discuss this approach and apply it to the Alpha algorithm [11], which uses heuristics about the relations seen between pairs of tasks in the log, to construct a Petri net. To compare this non-probabilistic model against the ground truth distribution, we convert the net to a PDFA by labelling its reachability graph (RG) with maximum likelihood probabilities obtained from the mining log. This allows us to satisfy the accuracy constraint.

We do not address the time constraint, since Alpha has low complexity and although the time to generate the RG is exponential in the number of states, we use only simple acyclic models. Business process models are in general relatively simple, but further work is needed to validate the efficiency of our approach.

4.3 Methods to Detect Process Change

We mine repeatedly from sublogs, using a ‘sliding window’, and compare the distribution generated by the mined model with the ground truth distribution. There are many measures of difference between probability distributions, such as Euclidean distance, Kullback-Leibler Divergence. Some can be efficiently calculated from PDFAs, but it is not clear what distance is statistically significant. Instead, we use statistical tests for detecting that the mined distribution, or its PDFa representation, has changed significantly from the ground truth.

The count of each unique trace x in the log can be modelled as a Binomially-distributed random variable, since any trace in the log will either be x , or not. The same is true of the number of times each arc in the PDFa is used in generating the log: each trace will either use that arc, or not (at present we assume acyclic models). If the number of traces is large enough relative to the trace/arc probabilities, the Binomial can be approximated by the Normal distribution.

Goodness of Fit Test on the Distribution: The sum of k Normally distributed random variables follows a Chi^2 distribution with $k - 1$ degrees of freedom. Thus we can use the Chi^2 test to determine whether the difference between the count of each unique trace found in the sample, and the expected count, is likely under the assumption that the log was drawn from the ground truth distribution. The so-called p -value gives the probability that the Chi^2 distribution would exceed the measured value, indicating that with probability $1 - p$, the process has changed.

Bounds and Hypothesis Tests on the PDFa: We expect the PDFa from the mining result to have the same state structure as the ground truth PDFa (making assumptions about the ground truth PDFa and the mining algorithm). The Hoeffding inequality upper bounds the probability of a sum of random variables deviating from its expected value. As [4], we use this to compare the probability of each arc from equivalent states in the models, by comparing the sum of the Bernoulli variables that each trace involves use of that arc.

Secondly, as [8] we use a hypothesis test to test how likely it is that an arc would be used the number of times indicated by its probability in the mined model, to generate the log, assuming the ground truth probability. Here the count is modelled as Binomial or Normal variable.

Bounds and Hypothesis Tests on Traces: The methods described for testing PDFa arcs can similarly be applied to process traces, so that we can use Hoeffding bounds or hypothesis tests to determine whether a process trace is likely to occur with the observed frequency, under the ground truth distribution.

5 Experimentation and Analysis

We used the example process of Fig.1. Using our method [14] the Alpha algorithm needs 44 traces to, with 99% probability, correctly mine a (non-probabilistic) Petri net with the correct structure. We randomly simulated the PDFa to produce an MXML¹ format log file of this size, and regularly updated it by simu-

¹ Mining eXtensible Markup Language, see www.processmining.org.

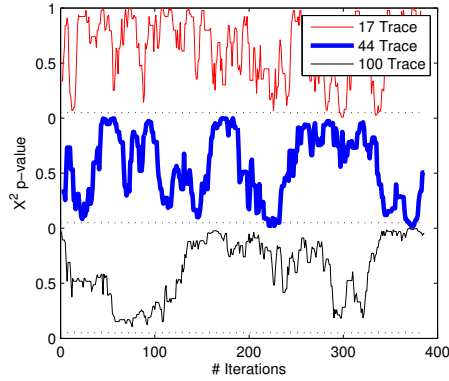


Fig. 2. Fluctuations in X^2 p-value over time, from unchanged source process.

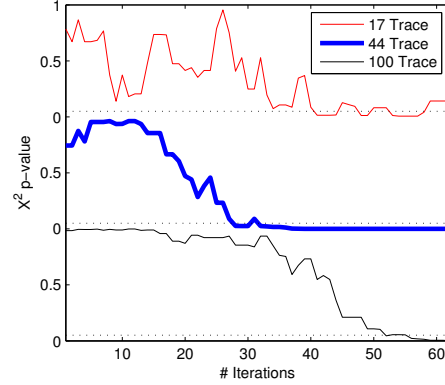


Fig. 3. Detection of XOR probability change using X^2 p-value.

lating one new trace and removing the oldest. This simulates a ‘sliding window’ onto a log file being updated in real time by a live process. Changes were introduced to the probabilities or structures in this PDFA. At each iteration, we used the Alpha algorithm² to mine a Petri Net from the current log and converted to a PDFA (section 4.2). We recorded distances between the distribution generated by this PDFA and the ground truth, and results of the tests in section 4.3.

We ran three experiments to test the hypotheses that (i) change is detectable using a variety of methods, (ii) more significant change is detected in fewer traces, and (iii) the predicted number of traces for mining the model is the optimum to use for detecting change, thus allowing detection in real time.

Since the Alpha algorithm mines only a Petri net structure (no probabilities), it needs a relatively small sample of traces, which exhibits high variance from the ground truth (Fig.2), resulting in high risk of false positives (incorrectly detecting change) or false negatives (not detecting true change). We did not take this into account beyond ensuring no false positives occurred before change was introduced, but it would affect the detection point. These initial results were also based on one test only of each sample. The main results seem clear, but are not statistically valid without averaging over multiple tests.

Varying Probabilities We varied probabilities in the XOR split B , and parallel split C . Small variations (< 0.1) were not detectable, although the distance measures increased. For the XOR split, change to $p(ab) = 0.7$ was discovered in 28 iterations, reducing to 9 for $p(ab) = 0.1$. Detection was first by X^2 (Fig.3), then by hypothesis test on strings (Fig.4) or arcs, and last by the Hoeffding tests. The looseness of the Hoeffding bound allows the string/arc frequencies to be more readily accepted as within confidence bounds given the ground truth.

The variation of AND probabilities was tested with probability of the structure in the model being 0.9 and then 0.1. The latter change was detected first

² implemented in the process mining tool ProM (www.processmining.org).

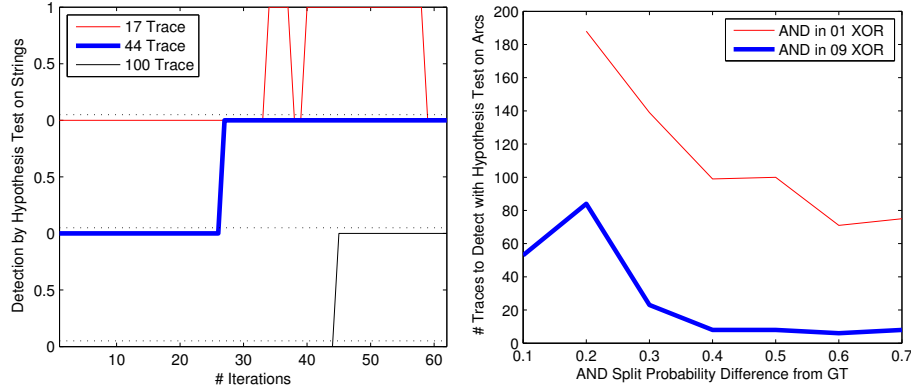


Fig. 4. Detection of XOR probability change using hypothesis test on strings. **Fig. 5.** AND change detection using hypothesis test on arcs, varying probabilities.

by arc differences (Fig.5), the string difference methods not detecting it at all. This is explained by the probability of traces passing through the AND structure being too low to detect significant changes, but for those that do, changes to arc usage are local and not affected by the global probability of the structure.

Varying amount of data We varied the amount of data in the ‘sliding window’. With 44 traces we see high variance in the probability distribution, seen in the large fluctuations in X^2 p-value in the centre graph of Fig.2. The lower graph shows that the frequency and amplitude of these changes is reduced with 100 traces, with no significant (0.05) p-values. The cost is slower detection of change (Fig.3 and 4). Conversely, reducing the number of traces to 17, change can be detected sooner, but with higher risk of false positive or false negative.

6 Conclusion and Future Work

We examined various methods for detecting change in a running process, with initial results showing that using the optimal amount of data to be confident that the mined process is correct, various statistical methods can be used to efficiently detect change in real time. The Chi^2 test allows earliest detection of change, except where the change is in a low probability part of the model, when hypothesis testing the arc frequencies is a better choice.

Further work is needed to determine how to choose the optimal method to detect change, to understand the effect of variation in the underlying distribution and the risk of falsely identifying or missing change, and to predict the time to detect change. Some distances between distributions can be efficiently calculated from PDFAs, so understanding of the significance of distance measures, would lead to more efficient methods for detecting change. More work is also needed to ensure the efficiency of the proposed method. Finally, the question remains, is process mining a better approach than simply analysing the log distributions?

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